

Key features

Configurable receiver, scalable for future requirements.

Available in base & rover, rover only, or base only configurations.

Trimble[®] Inertial Platform[™] (TIP[™]) technology for magnetically immune IMU-based tilt compensation.

Trimble lonoGuard[™] technology for mitigation of ionospheric GNSS signal disruptions. Trimble ProPoint[®] GNSS positioning engine for improved accuracy and productivity in challenging GNSS conditions.

Trimble Maxwell[™] 7 GNSS ASIC.

9 GB internal memory.

Trimble xFill[®] correction outage technology.

Supports Trimble CenterPoint[®] RTX corrections for RTK level accuracy worldwide via satellite/IP.

Military-grade ultra-rugged design, IP68 rating.

Optimized for Trimble Access[™] field software.

Find out more at: geospatial.trimble.com/r780



SPEC SHEET

Trimble R780

GNSS system

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PERFORMANCE SPECIFICATI	ONS	
GNSS TECHNOLOGY		
	integration with Trimble ProPoint GNSS technology	ed positioning in challenging environments ¹ and inertial measurement I traceability with Trimble TIP [™] technology IMU-based tilt heric GNSS signal disruptions
	Spectrum Analyzer to troubleshoot GNSS jamming Anti-spoofing capabilities Supports Trimble Internet Base Station Service (IBSS) fo Japanese LTE Filtering below 1510 MHz allows antenna	or streaming RTK corrections using Trimble Access 2023.10 or later s to be used 100 m away from Japanese LTE cell tower
	Iridium Filtering above 1616 MHz allows the antenna to	be used 20 m away from Iridium transfer
SATELLITE TRACKING		
	GPS: L1C, L1 C/A, L2E (L2P), L2C, L5 GLONASS: L1C/A, L1P. L2C/A, L2P, L3 Galileo: E1, E5A, E5B and E5AltBOC, E6 ² BeiDou: B1, B2, B3, B1C, B2A QZSS: L1 C/A, L1C, L1S, L2C, L5, LEX/L6 IRNSS: L5 SBAS: L1 C/A (EGNOS/MSAS GAGAN/SDCM), L1 C/A and L-Band: Trimble RTX	i L5 (WAAS)
POSITIONING PERFORMANC		
STATIC GNSS SURVEYING		
High-Precision Static		
	Horizontal	3 mm + 0.1 ppm RMS
	Vertical	3.5 mm + 0.4 ppm RMS
Static and Fast Static		
	Horizontal	3 mm + 0.5 ppm RMS
	Vertical	5 mm + 0.5 ppm RMS
REAL TIME KINEMATIC SURVEYI	NG	
Single Baseline < 30 km	Horizontal	8 mm + 1 ppm RMS
	Vertical	15 mm + 1 ppm RMS
Network RTK ⁴		
	Horizontal	8 mm + 0.5 ppm RMS
	Vertical	15 mm + 0.5 ppm RMS
	RTK start-up time for specified precisions⁵	2 to 8 seconds
TRIMBLE INERTIAL PLATFORM (TIP) TECHNOLOGY	
TIP Compensated Surveying ⁶		
	Horizontal	RTK + 8 mm + 0.5 mm/° tilt (up to 30°) RMS
MIL Integrity Monitor	Horizontal Riss monitoring	RTX + 8 mm + 0.5 mm/° tilt (up to 30°) RMS
IMU Integrity Monitor TRIMBLE RTX CORRECTION SER'	Bias monitoring	Temperature, age and shock
CenterPoint RTX ⁷		
	Horizontal	2 cm RMS
	Vertical	5 cm RMS
	RTX convergence time for specified precisions in Trimble RTX Fast regions RTX convergence time for specified precisions in non	< 1 min
	RTX Fast regions RTX QuickStart convergence time for specified precisions	< 3 min < 5 min
TRIMBLE xFILL ⁸		
	Horizontal	RTK ⁹ + 10 mm/minute RMS
	Vertical	RTK ⁹ + 20 mm/minute RMS
TRIMBLE xFILL PREMIUM ⁸		
	Horizontal	3 cm RMS
	Vertical	7 cm RMS

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POSITIONING PERFORMANC	E ³ Cont.		
CODE DIFFERENTIAL GNSS POSI			
	Horizontal	0.25 m + 1 ppm RMS	
	Vertical	0.50 m + 1 ppm RMS	
	SBAS ¹⁰	Typically < 5 m 3DRMS	
HARDWARE			
PHYSICAL			
Dimensions (W×H)	13.0 cm x 13 cm (5.5 in x 5.1 in) in	cluding connectors	
Weight	13.9 cm x 13 cm (5.5 in x 5.1 in) including connectors 1.55 kg (3.42 lb) receiver only including radio and battery		
0	1.55 kg (5.42 lb) receiver only including radio and battery		
Temperature ¹¹	Operating	-40 °C to +65 °C (-40 °F to +149 °F)	
	Operating		
n statu	Storage	-40 °C to +75 °C (-40 °F to +167 °F)	
Humidity		100%, condensing	
Ingress protection		IP68 Certified per IEC-60529: waterproof/dustproof (1 m submersion for 1 hou	
Shock and vibration			
	Pole drop	Designed to survive a 2 m (6.6 ft) pole drop onto concrete	
	Shock	Non-operating: 75 Gs at 6msec	
	Shock	Operating: 40 Gs at 10msec	
	Vibration	Mil-Std-810G, FIG 514.6E-1 Cat 24, Mil-Std-202G, FIG 214-1, Condition D	
ELECTRICAL			
	Internal	Rechargeable, removable Lithium-ion battery in internal battery compartment	
		Internal battery operates as a UPS during an ext power source failure	
		Internal battery will charge from external power source as long as source can	
		support the power drain and is more than 11.8 VDC	
		Integrated charging circuitry	
	External	External power input with over-voltage protection on Port 1	
		(7-pin Lemo 2-key) Minimum 10.8 V, Maximum 28 VDC, shutdown optimized for 12 V lead acid battery operation	
		Power source supply (Internal/External) is hot-swap capable in the event of power source removal or cut off	
		DC external power input with over-voltage protection on Port 1 (Lemo)	
	Dower consumption	Receiver automatically turns on when connected to external power	
	Power consumption	3.2 W in rover mode with internal receive radio ¹²	
O		5.2 W in base mode with internal 0.5 W transmit radio	
Operating times on internal battery ¹³			
	Rover Rose station	5.5 hours; varies with temperature	
	Base station	5.5 hours; varies with temperature	
	450 MHz systems	Approximately 4 hours; varies with temperature	
COMMUNICATIONS AND DA	900 MHz systems	Approximately 4 hours; varies with temperature	
		SB. Optional USB to RS232 serial cable. Receiver supports RNDIS communications	
Lemo (Serial 1)	over USB		
Wi-Fi®	Client or Access Point. Receive or transmit corrections. Wi-Fi b/g/n		
Bluetooth® wireless technology	Fully-integrated sealed 2.4 GHz Bluetooth module		
ntegrated radios (optional)	Fully-integrated, fully-sealed internal 403-473 MHz; Internal 900 MHz; Rx/Tx		
Channel spacing (450 MHz)	12.5 kHz or 25 kHz spacing available		
Sensitivity (450 MHz)	-114 dBm (12 dB SINAD)		
450 MHz output power	0.5 W, 2.0 W, depending on the local required licensing.		
Frequency approvals (403-473 MHz) Positioning rates	Worldwide, depending on the local required licensing. 1 Hz, 2 Hz, 5 Hz, 10 Hz, and 20 Hz		
Data storage	9 GB internal data logging. Moving		
-	CMR+, CMRx, RTCM 2.1, RTCM 2.3, RTCM 3.0, RTCM 3.1, RTCM 3.2 input and output		
Data format	24 NMEA outputs, GSOF, RT17, and RT27 outputs		

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CERTIFICATIONS		
	FCC Part 15 Subpart B (Class B Device), Part 15.247, Part 90	
	Canadian ICES-003 (Class B), RSS-GEN, RS-102, RSS-247	
	IEC62368-1 2nd Edition	
	CISPR 32, EN 55032, EN55035	
	RCM mark, AS/CISPR 32, AS/NZS 4768	
	Japan MIC	
	CE mark, Radio Equipment Directive (RED 2014/53/EU)	
	RoHS compliance	
	WEEE compliance	
TRIMBLE PROTECTED PROTECTION PLANS		

Add a Trimble Protected protection plan for worry-free ownership over and above the standard Trimble product warranty. Added enhancements include coverage for wear & tear, environmental damage, and more. Accidental damage is covered with Premium plans, available only at point-of-sale in selected regions. For details, visit trimbleprotected.com or contact a local Trimble distributor.

- 1 Challenging GNSS environments are locations where the receiver has sufficient satellite availability to achieve Chaining GNSS environments are locations where the receiver has sufficient satellite availability to achieve minimum accuracy requirements, but where the signal may be partly obstructed by and/or reflected off of trees, buildings, and other objects. Actual results may vary based on user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability, and level of multipath and signal occlusion. The current capability in the receivers is based on publicly available information. As such, Trimble cannot guarantee that these receivers will be fully compatible with a future generation of Galileo satellites or signals. Precision and reliability may be subject to anomalies due to multipath, obstructions, satellite geometry, and atmospheric conditions. The specifications stated recommend the use of stable mounts in an open sky view, FMI and multipath clean environment to ontimal GNSC constellation configurations, along with the use of stuper.
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- atmospheric conditions. The specifications stated recommend the use of stable mounts in an open sky view, EMI and multipath clean environment, optimal GNSS constellation configurations, along with the use of survey practices that are generally accepted for performing the highest-order surveys for the applicable application including occupation times appropriate for baseline length. Baselines longer than 30 km require precise ephemeris and occupations up to 24 hours may be required to achieve the high precision static specification. Network RTK PPM values are referenced to the closest physical base station. May be affected by atmospheric conditions, signal multipath, obstructions and satellite geometry. Initialization reliability is continuously monitored to ensure highest quality. TIP references the overall positioning error estimate at the tip of the surveying pole throughout the tilt compensation range. RTK refers to the estimated horizontal precision of the underlying GNSS position, which is dependent on factors that affect GNSS solution quality. The 8 mm constant error component accounts for residual misalignment between the vertical axes of the receiver and the built-in Inertial Measurement Unit (IMU) after factory calibration, assiming the receiver is mounted on a standard 2 m carbon fiber range pole which is properly
- 6 factory calibration, assuming the receiver is mounted on a standard 2 m carbon fiber range pole which is properly calibrated and free from physical defects. The tilt-dependent error component is a function of the quality of the computed tilt azimuth, which is assumed here to be aligned using optimal GNSS conditions. For best IMU tilt compensated results, perform a pole bias adjustment.
- MS performance based on repeatable in field measurements. Achievable accuracy and initialization time may vary based on type and capability of receiver and antenna, user's geographic location and atmospheric activity, scintillation levels, GNSS constellation health and availability and level of multipath including obstructions such as large trees and buildings.
- Accuracies are dependent on GNSS satellite availability. xFill positioning without an xFill Premium subscription ends after 5 minutes of radio downtime. xFill Premium will continue beyond 5 minutes providing the solution has converged, with typical precisions not exceeding 3 cm horizontal, 7 cm vertical. xFill is not available in all regions, check with your local sales representative for more information.
- 9 RTX refers to the last reported precision before the correction source was lost and xFill started. 10 Depends on SBAS system performance. 11 Receiver will operate normally to -40 °C, internal batteries are rated from -20 °C to +60 °C (ambient +50 °C).
- Tracking GPS, GLONASS and SBAS satellites.
 Varies with temperature and wireless data rate. When using a receiver and internal radio in the transmit mode, it is recommended that an external 6 Ah or higher battery is used.

Specifications subject to change without notice.





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